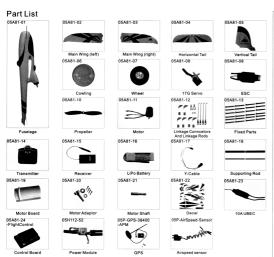
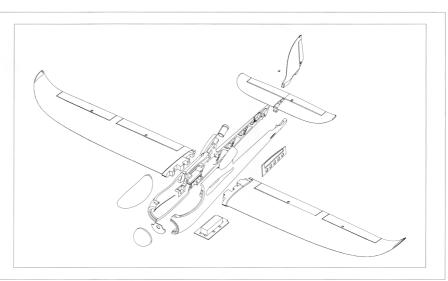
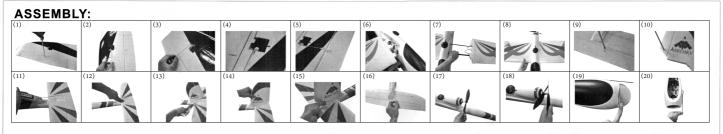


DIRECTIONS FOR ASSEMBLY AND ADJUSTMENT







(1)(2)(3)(4)(5) Install the linkage connectors and connect the linkage rods on the main wings.

(6) Connect the Y-Cable between the main wings.

(7)(8) Insert the supporting rod into the main wings.

(9)(10) Install the linkage connectors on the tail wing and vertical wing.

(11)(12)(13)(14) Glue the tail wing and vertical wing.

(15)(16) Connect the linkage rods for the rudder and elevator.

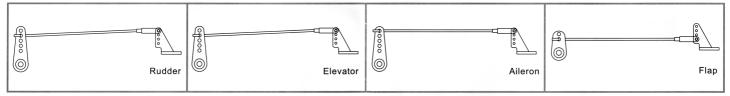
(17)(18) Install the propeller.

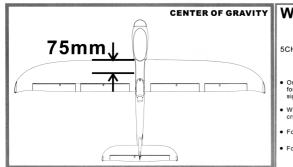
(19) Install and secure the cowling with tape.

(20) Point the airspeed tube straight forward to allow more accurate measurement of air speed.

SETTING UP THE RADIO: Use following set up for the third party radio system: Aileron: NOR, Elevator: NOR, Rudder: NOR

The main control board supports advanced programs such as "Mission planner", " Andropilot " for routine planning and ground station features (use USB or 3DRF connection)





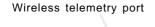
Warning:

RTL(Return to location) 5CH Flight Mode: ← STABILIZE(Default) 6CH FLAP Manual

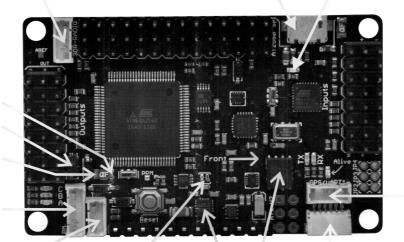
- On the first couple of flights at a new location, do not switch to the RTL flight mode, the GPS and MAG module need to make adjustment for the the new location automatically. Before switch to the RTL flight mode, make sure the GPS module acquires enough GPS satellite signal (minimum 3 satellites). The red led on the GPS module starts showing green flashes indicating enough GPS signal is acquired.
- When switch to the RTL flight mode, the airplane should automatically return to the unlock position (where the GPS signal was acquired) and
 cruise in a 75 feet radius circle at around 200 feet in altitude. The return path should be free of tree and building.
- For more accurate RTL position, wait additional 30 seconds at the desired position before unlocking the airplane.
- For better GPS signal reception, 1500 feet radius clearance of flying field is required.







Status LED USB port connector



New style GPS port

External I2C port

Power port

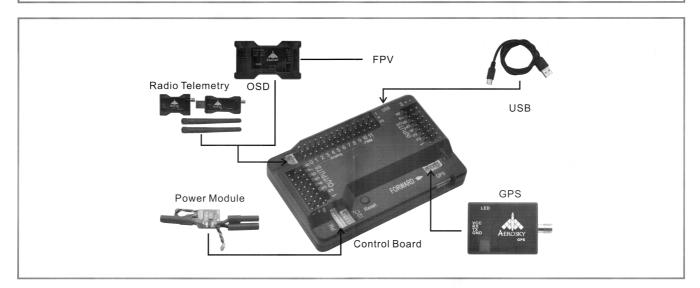
Fuse

Measure Vcc here Diode

> Optional to use external magnetometer On board Mag

Dataflash

Old style GPS port













Charge the Li-Po battery pack

Lithium Polymer (LiPo) Battery Warnings

