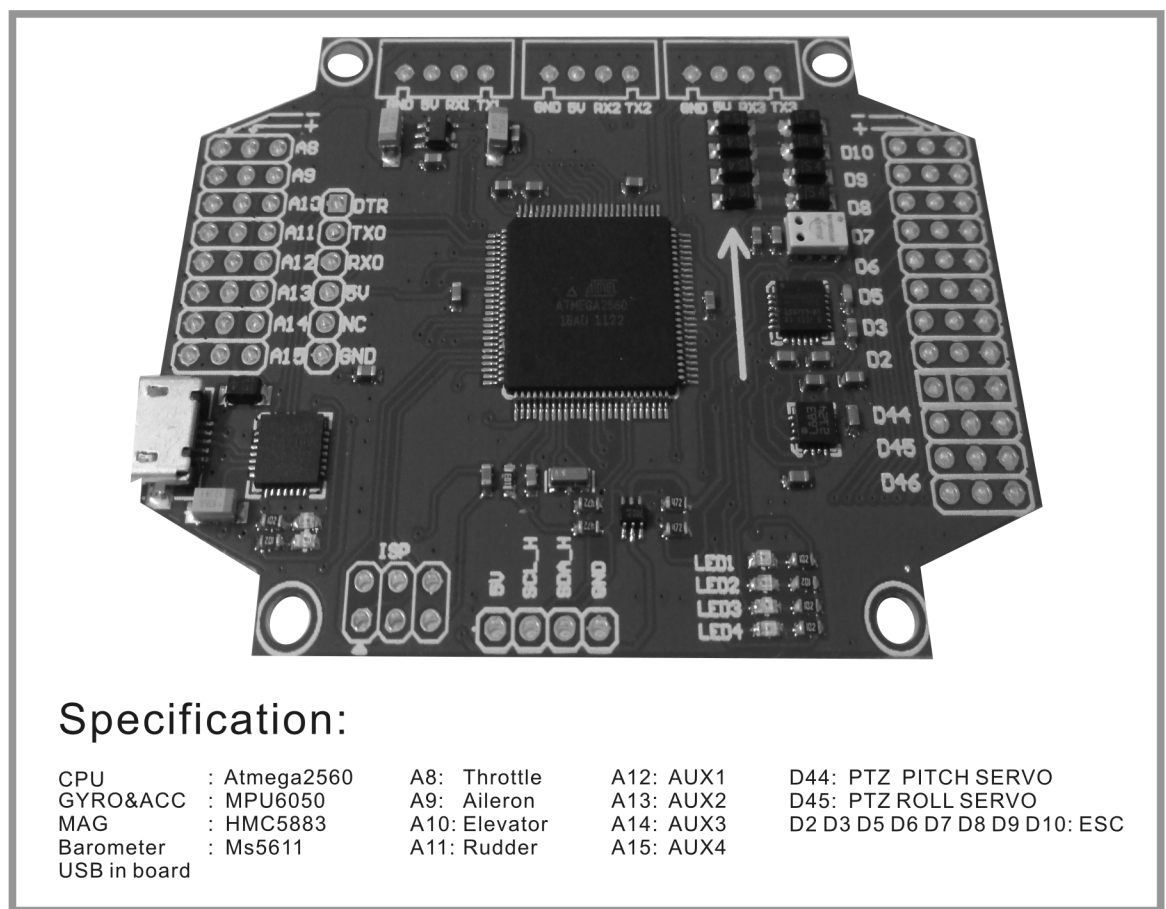
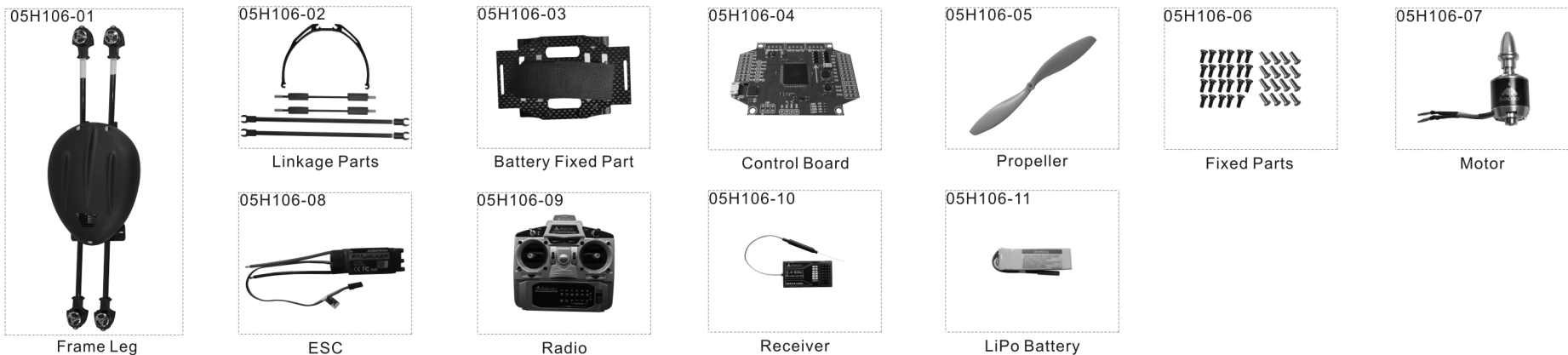
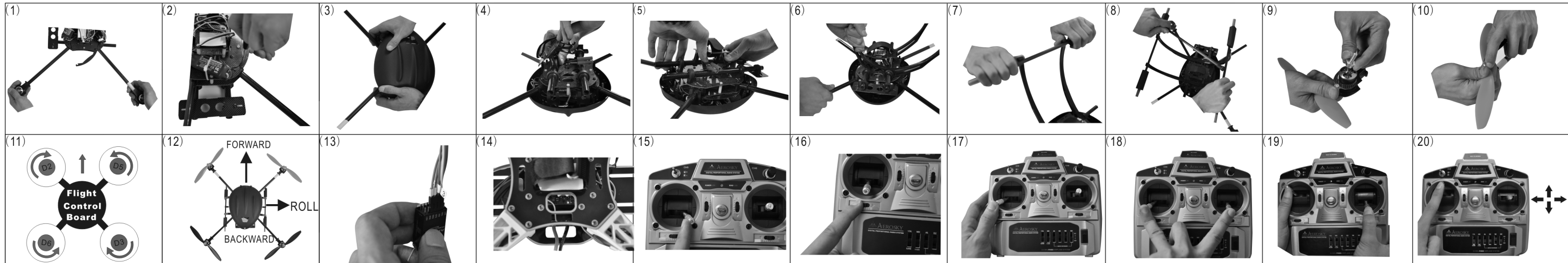


DIMENSION : 600mm (23.62 inches)
HEIGHT : 310mm (12.2 inches)
WEIGHT : 1150g (40.56 oz)
BATTERY : 14.8V Lithium Polymer Battery
POWER SYSTEM : Outrunner Brushless Motor
RC SYSTEM : 6 Channel And 4 Brushless ESC

Part List



ASSEMBLY:



- (1) Expand the carbon frame.
- (2) Secure the carbon frame.
- (3) Install the canopy cover.
- (4)(5) Assemble the battery compartment.
- (6)(7)(8) Assemble the landing gear.
- (9) Install the motor adaptor.
- (10) Install the propeller.

PROPELLER:
Install and tightly secure the propellers according to the diagram (Fig.11)

FLY MODE:
The multicopter operates in "X" mode. The red legs indicate the forward direction; the white legs indicate the backward direction (Fig. 12)

SETTING UP THE RADIO:
Use the following setting for third party radio system:
Aileron: REV, Elevator: NOR, Rudder: REV

CONNECTING THE RECEIVER:
Connect according to the number label on the wires:
No. 1: Aileron, No.2: Elevator, No.3: Throttle, No.4: Rudder, No.5: Level, No.6: Baro&Care Free (Fig.13)

CONNECTING THE BATTERY:
Place the multicopter on a flat place, connect the battery, motors should produce the "dee dee" tone, the LED should turn on, and the LED1 should flash for two seconds and turn off (indicating the multicopter is in Lock Mode). (Fig.14)

UNLOCKING THE MULTICOPTER:
You can unlock the multicopter after connecting the battery. Move the left control stick to the lower right corner, the LED1 should turn solid and propeller should turn on (indicating the multicopter is in the Unlock Mode). You can push the throttle slowly to let the multicopter takes off. If unlock fails, adjust the direction trimming and unlock again (Fig.15)

LOCKING THE MULTICOPTER:
For safety, please lock the multicopter after each operation. Move the left control stick to the lower left corner (Fig. 17). The LED1 should turn off (indicating the multicopter is in the Lock Mode).

ADJUSTING THE AUTO STABLIZED FLIGHT SYSTEM:
If the multicopter does not fly stable, use the following steps to adjust the auto stabilized flight system.
Place the multicopter on a flat surface.

- Adjusting the gyro:
- 1) Put the multicopter in lock mode;
 - 2) Move the left control stick to the lower left corner position and the right control stick to the lower center position. The LED1 should flash for 5 seconds (indicating the auto stabilized flight system is calibrating). (Fig.18)
- Adjusting the ACC:
- 1) Put the multicopter in lock mode.
 - 2) Move the left control stick to the upper left corner position and the right control stick to the lower center position. The LED1 should flash for 5 seconds (indicating the auto stabilized flight system is calibrating). (Fig.19)
- Adjusting the control stick center position:
- 1) Put the multicopter in lock mode
 - 2) Move the left control stick to the upper center position and the right control stick to the maximum position of all directions. The LED1 should keep flashing.
 - 3) Let the right control stick back to the center position, the LED1 should stop flashing. Calibration completed. (Fig.20)

CH 5 (AUX1) Maintain flying level automatically
Set the AUX1 control on an on/off toggle switch.
"-100": onlock
"+100": unlock
Switch to onlock mode, put the elevator and aileron control stick on the center position, the multicopter should maintain flying level automatically.

CH 6 (AUX2) Baro & CareFree (Simple)
In Carefree(Simple) mode, the multicopter always flies according to the compass direction that is set at the launching position, not your control orientation. If you launch the multicopter facing North as the forward direction, North is always the forward direction for the control stick. You don't need to worry about the orientation of the multicopter.
Set the AUX2 control on a three stages toggle switch.
"-100": Baro&Care Free on
"0" : Baro on
"+100" : Baro&Care Free off
The multicopter should maintain the flying height at the position you turn the Baro mode on. The throttle control should react slowly to input at this time (this feature can be affected by weather, power level, and wind).
The multicopter should fly according to compass direction when the carefree mode is on.

Connecting the PTZ
D44: PTZ pitch servo.
D45: PTZ roll servo.



AeroSky guarantees this product to be free of manufacturing faults and material defects. This product has been checked and fine tuned individually by professional pilot and quality control pilot. The warranty does not cover any component parts damaged by use and modification. Please visit <http://www.aeroskyrc.com> for updated product information.

This product is not a toy. It is not recommended for children under 14 years old and any minor should be accompanied by an adult when operating. This product is a precision machine that requires proper assembly and setup to avoid accidents. Failure to take caution when operating this product may result in serious injury or property damage. It is the owner's responsibility to operate this product in a safe manner. Manufacturer and its distributors are not responsible in any way for any and all bodily injury(s) and/or property damage that may occur from the use of or caused by in any way of this product.

